

**Amendments to the Claims:**

1. (currently amended) A method for reducing a blocking artifact in a video stream, the method comprising:

5       calculating an activity value representing the local activity around a block boundary between a plurality of adjacent blocks in the video stream;

          determining a region mode for the block boundary according to the activity value;

10       adaptively determining a plurality of thresholds according to at least differences in the values of quantization parameters (QPs) of the adjacent blocks; ~~and~~

          filtering a plurality of pixels around the block boundary to reduce the blocking artifact according to the region mode and the plurality of thresholds; and

15       adaptively determining a first threshold TH0\_INTRA, a third threshold TH0\_INTER, a fourth threshold TH1\_INTRA, a fifth threshold TH2\_INTRA, a sixth threshold TH1\_INTER, and a seventh threshold TH2\_INTER; wherein when determining the first, third, fourth, fifth, sixth, and seventh thresholds, at least  
20       taking into account differences in QPs of the adjacent blocks.

2. (cancelled)

3. (currently amended) The method of claim 1 ~~claim 2~~, further taking into account a user  
25       defined offset (UDO) allowing the first, third, fourth, fifth, sixth, and seventh threshold levels to be adjusted according to the UDO value.

4. (original) The method of claim 3, wherein:

the first threshold TH0\_INTRA is calculated as:

$$TH0\_INTRA = -2 + (QP1 + QP2) + 2 \cdot UDO;$$

the third threshold TH0\_INTER is calculated as:

5  $TH0\_INTER = -2 + (QP1 + QP2) - 2 \cdot MVI - 2 \cdot BFlag + 2 \cdot UDO;$

the fourth threshold TH1\_INTRA is calculated as:

$$TH1\_INTRA = -1 + \frac{1}{2} \cdot (QP1 + QP2) + \frac{1}{2} \cdot |QP1 - QP2| + UDO;$$

the fifth threshold TH2\_INTRA is calculated as:

$$TH2\_INTRA = -2 + (QP1 + QP2) + |QP1 - QP2| + 2 \cdot UDO;$$

10 the sixth threshold TH1\_INTER is calculated as: and

$$TH1\_INTER = a + \frac{1}{2} \cdot (QP1 + QP2) + \frac{1}{2} \cdot |QP1 - QP2| + 2 \cdot MVI - 2 \cdot BFlag + UDO;$$

the seventh threshold TH2\_INTER is calculated as:

$$TH2\_INTER = a + (QP1 + QP2) + \frac{1}{2} \cdot |QP1 - QP2| - 2 \cdot MVI - 2 \cdot BFlag + 2 \cdot UDO;$$

wherein MVI represents the motion vector indicator; if the picture is B-picture,

15 BFlag is set to 1, otherwise, BFlag is set to 0; and if the 8x8 block boundary is also a macroblock (MB) boundary,  $a$  is set to -1, otherwise,  $a$  is set to -3.

5. (original) The method of claim 4, wherein calculating the activity value comprises summing absolute differences between pixels  $V_l$  around the block boundary as follows:

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$$ACTIVITY = \sum_{l=4}^6 |v_l - v_{l+1}| + \sum_{l=8}^{10} |v_l - v_{l+1}|$$

6. (original) The method of claim 5, wherein:

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if at least one of the adjacent blocks is an intra-coded block:

if the activity value is greater than the first threshold TH0\_INTRA,  
determining the region mode to be an active region;

5 if the activity value is less than the first threshold TH0\_INTRA but greater  
than a second threshold, determining the region mode to be a smooth region;  
and

10 if the activity value is less than the second threshold, determining the region  
mode to be a dormant region; and

if none of the adjacent blocks are intra-coded blocks:

15 if the activity value is greater than the third threshold TH0\_INTER,  
determining the region mode to be an active region;

if the activity value is less than the third threshold TH0\_INTER but greater  
than the second threshold, determining the region mode to be a smooth region;  
and

20 if the activity value is less than the second threshold, determining the region  
mode to be a dormant region.

25 7. (original) The method of claim 6, wherein the second threshold is fixed at a  
predetermined value.

8. (original) The method of claim 7, wherein the predetermined value is 6.

9. (original) The method of claim 6, further comprising:

if the region mode is active region,

5 if at least one of the adjacent blocks is an intra-coded block and a high frequency component ( $c_3$ ) is less than the fourth threshold TH1\_INTRA, or if none of the adjacent blocks is an intra-coded block and the high frequency component ( $c_3$ ) is less than the sixth threshold TH1\_INTER, filtering the pixels around the block boundary using a first filter;

10 if the region mode is smooth region,

if at least one of the adjacent blocks is an intra-coded block and the absolute value of the difference of the pixel values on either side of the block boundary is less than the fifth threshold TH2\_INTRA, or if none of the adjacent blocks is an intra-coded block and the absolute value of the difference of the pixel values  
15 on either side of the block boundary is less than the seventh threshold TH2\_INTER, filtering the pixels around the block boundary using a second filter; and

if the region mode is dormant region,

20 if at least one of the adjacent blocks is an intra-coded block and the absolute value of the difference of the pixel values on either side of the block boundary is less than the fifth threshold TH2\_INTRA, or if none of the adjacent blocks is an intra-coded block and the absolute value of the difference of the pixel values on either side of the block boundary is less than the seventh threshold  
25 TH2\_INTER, filtering the pixels around the block boundary using a third filter.

10. (original) The method of claim 9, wherein the high frequency component ( $c_3$ ) is calculated using pixels  $v_6$ ,  $v_7$ ,  $v_8$ ,  $v_9$  around the block boundary as follows:

$$c_3 = (v_6 - v_7 + v_8 - v_9)/2.$$

11. (original) The method of claim 9, wherein the first filter is a one dimensional filter  
formed by using a 4-point Hadamard Transform (HT), wherein the high frequency  
5 coefficient of the HT is reduced to 0 for frame-coded pictures.

12. (original) The method of claim 9, wherein the first filter is a one dimensional filter  
formed by using a 4-point Hadamard Transform (HT), wherein the high frequency  
coefficient of the HT is reduced to one half for field-coded pictures.

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13. (original) The method of claim 9, wherein the filtered pixels are further refined by  
adjusting a pixel quantized with a larger QP to have more change in value than a  
pixel quantized with a smaller QP.

15 14. (original) The method of claim 13, wherein a first weighting value WT1 and a  
second weighting value WT2 are used for adjusting the filtered pixels and are  
obtained from a first quantization parameter QP1 of a first adjacent block and a  
second quantization parameter QP2 of a second adjacent block as follows:

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$$WT1 = QP1 / (QP1 + QP2) \quad , \quad WT2 = QP2 / (QP1 + QP2)$$

15. (original) The method of claim 8, wherein if the quantization parameters (QPs) of  
the adjacent blocks are the same, symmetric second and third filters are used to filter  
the pixels around the block boundary for smooth and dormant region modes,  
25 respectively; and

if the QPs of the adjacent blocks are not the same, asymmetric second and third

filters are used to filter the pixels around the block boundary for smooth and dormant region modes, respectively.

16. (original) The method of claim 15, further comprising:

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when the region mode is smooth region and the QPs of the adjacent blocks are the same, filtering the pixels around the block boundary with an N-tap symmetric second filter;

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when the region mode is smooth region and the QPs of the adjacent blocks are not the same, filtering the pixels around the block boundary with an M-tap asymmetric second filter;

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when the region mode is dormant region and the QPs of the adjacent blocks are the same, filtering the pixels around the block boundary with a K-tap symmetric third filter; and

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when the region mode is dormant region and the QPs of the adjacent blocks are not the same, filtering the pixels around the block boundary with an L-tap asymmetric third filter.

17. (original) The method of claim 16, wherein:

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N=5 and the symmetric second filter is  $[1\ 3\ 8\ 3\ 1]/16$ ;

M=5 and the asymmetric second filter is  $[1\ 2\ 8\ 3\ 2]/16$  and  $[2\ 3\ 8\ 2\ 1]/16$ ;

K=5 and the symmetric third filter is  $[1\ 2\ 2\ 2\ 1]/8$ ; and

$L=5$  and the asymmetric third filter is  $[1\ 1\ 2\ 2\ 2]/8$  and  $[2\ 2\ 2\ 1\ 1]/8$ .

18. (original) The method of claim 9, wherein filtering the pixels around the block  
5 boundary comprises first filtering the pixels at the block boundary and next filtering  
pixels not adjacent to the pixels at the block boundary.

19. (original) The method of claim 1, further comprising if the video stream comprises  
interlaced video, performing an interpolation operation to estimate pixel values in  
10 an interlaced field before filtering the pixels around the block boundary.

20. (original) The method of claim 1, further comprising determining a filtering range  
according to block coding types of the adjacent blocks in the video stream; wherein  
the filtering range specifies a number of pixels to filter around the block boundary.  
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21. (original) The method of claim 20, wherein according to the block coding types of  
the adjacent blocks in the video stream, determining the filtering range to be up to  
eight pixels around the block boundary.

20 22. (original) The method of claim 20, wherein determining a filtering range according  
to the block coding types of the adjacent blocks in the video stream further  
comprises:

25 if at least one of the adjacent blocks is an intra-coded block, determining the  
filtering range to be up to four pixels around the block boundary; and

if none of the adjacent blocks are intra-coded blocks, determining the filtering range  
to be up to eight pixels around the block boundary.

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23. (original) The method of claim 1, wherein the video stream is an MPEG video stream.